User stories:

1. As a user

I want to select objects to be moved automatically

So that I can automate loading and unloading systems.

1. As a DoBot

I want to receive target coordinates

So that I can grab and move objects onto my conveyor belt.

1. As a camera

I want to detect and identify different shapes, colors and positions

So that other entities can use this information for their needs.

1. As a GUI

I want to show information in a clear way and receive information

So that a user can read and give information to and from the system.